

## A Roe-type linearization for the gas dynamics equations

We focus, as we did before, on the case of a polytropic ideal gas:

$$p = (\gamma - 1) \rho \varepsilon, \quad \varepsilon = C_v T.$$

We propose to seek for a Roe-type linearization of the form

$$A(u_L, u_R) = \nabla_u f(\bar{u}(u_L, u_R)) \quad u = (\rho, \rho u, p \varepsilon)$$

where  $\bar{u}$  will be such that  $\bar{u}(u, u) = u$ . Doing so, (ii) and (iii) are automatically satisfied provided that  $\bar{u}(u_L, u_R)$  belongs to the phase space. It remains to check the property (i), namely

$$f(u_R) - f(u_L) = A(u_L, u_R) (u_R - u_L).$$

We can easily show that the Jacobian matrix  $\nabla_u f$  is given by

$$\nabla f(u) = \begin{pmatrix} 0 & 1 & 0 \\ (\gamma-3) \frac{u^2}{2} & -(\gamma-3)u & (\gamma-1) \\ u \left( (\gamma-1) \frac{u^2}{2} - H \right) & H - (\gamma-1)u^2 & \gamma u \end{pmatrix}$$

with  $H = h + \frac{u^2}{2}$  and  $h = \varepsilon + p/\rho = \varepsilon + (\gamma-1)\varepsilon = \gamma\varepsilon$

We then look for  $\bar{u}$  and  $\bar{H}$  such that

$$\begin{pmatrix} (\rho u)_R - (\rho u)_L \\ (\rho u^2 + p)_R - (\rho u^2 + p)_L \\ (\rho \varepsilon + p)_R - (\rho \varepsilon + p)_L \end{pmatrix} = \begin{pmatrix} 0 & 1 & 0 \\ (\gamma-3) \frac{\bar{u}^2}{2} & -(\gamma-3)\bar{u} & (\gamma-1) \\ \bar{u} \left( (\gamma-1) \frac{\bar{u}^2}{2} - \bar{H} \right) & \bar{H} - (\gamma-1)\bar{u}^2 & \gamma \bar{u} \end{pmatrix} \begin{pmatrix} p_R - p_L \\ (\rho u)_R - (\rho u)_L \\ (\rho \varepsilon)_R - (\rho \varepsilon)_L \end{pmatrix}$$

The first component is clearly satisfied.

The second one writes

$$\begin{aligned}
 [u^2 p] &= \frac{\delta-3}{2} \bar{u}^2 [p] - (\delta-3) \bar{u} [pu] + (\delta-1) \left\{ \frac{[pu^2]}{2} + \frac{[p]}{\delta-1} \right\} \\
 &= \frac{\delta-3}{2} \bar{u}^2 [p] - (\delta-3) \bar{u} [pu] + [p] + \frac{\delta-1}{2} [pu^2]
 \end{aligned}$$

$$\text{ie } \frac{3-\delta}{2} [pu^2] = (\delta-3) \bar{u} [pu] - \frac{3-\delta}{2} \bar{u}^2 [p]$$

Remark that it is always possible to write, if  $u_L \neq u_R$ ,

$$\bar{u} = \alpha u_L + (1-\alpha) u_R =: \vec{u}$$

while the Leibniz formula states that

$$[XY] = \vec{X} [Y] + \overleftarrow{Y} [X] \quad \text{with} \quad \begin{aligned} \vec{X} &= \alpha X_L + (1-\alpha) X_R \\ \overleftarrow{Y} &= (1-\alpha) Y_L + \alpha Y_R \end{aligned}$$

Then, the second component writes also

$$\frac{3-\delta}{2} [pu^2] = (\delta-3) \vec{u}^2 [p] + (\delta-3) \vec{u} \overleftarrow{p} [u] - \frac{3-\delta}{2} \vec{u}^2 [p]$$

$$\frac{3-\delta}{2} [pu^2] = \frac{3-\delta}{2} \vec{u}^2 [p] + (\delta-3) \vec{u} \overleftarrow{p} [u]$$

$$\text{or } [pu^2] = \vec{u}^2 [p] + 2 \vec{u} \overleftarrow{p} [u]$$

$$\begin{aligned}
 \text{But } [pu^2] &= [pu] \vec{u} + [u] \overleftarrow{pu} \\
 &= [p] \vec{u}^2 + [u] \overleftarrow{p} \vec{u} + [u] \overleftarrow{pu}
 \end{aligned}$$

so that we finally get

$$[u] (\overleftarrow{p} \vec{u} + \overleftarrow{pu}) = 2 \vec{u} \overleftarrow{p} [u]$$

$$\text{or } \overleftarrow{pu} = \vec{u} \overleftarrow{p}$$

This equation will allow us to define  $\alpha$ . Indeed, developing leads to the second order equation

$$(\rho_L - \rho_R) \alpha^2 + 2\alpha \rho_L - \rho_L = 0$$

which admits two roots if  $\rho_L \neq \rho_R$ :

$$\alpha = \frac{\sqrt{\rho_L}}{\sqrt{\rho_L} + \sqrt{\rho_R}}$$

$$\text{and } \alpha = \frac{\sqrt{\rho_R}}{\sqrt{\rho_L} - \sqrt{\rho_R}}$$

and only one root if  $\rho_L = \rho_R =: \rho$ :

$$\alpha = 1/2$$

Then, the only continuous way to define  $\alpha$  is to set

$$\alpha = \frac{\sqrt{\rho_R}}{\sqrt{\rho_L} + \sqrt{\rho_R}}$$

(the other choice gives  
discontinuity if  $\rho_L = \rho_R$ )

which gives

$$\bar{u} = \frac{\sqrt{\rho_L} u_L + \sqrt{\rho_R} u_R}{\sqrt{\rho_L} + \sqrt{\rho_R}}$$

Similar calculations on the third component lead to the definition

$$\bar{H} = \frac{\sqrt{\rho_L} H_L + \sqrt{\rho_R} H_R}{\sqrt{\rho_L} + \sqrt{\rho_R}}$$

These are the two only possible choices.

But of course, there exist other Roe-type linearizations based on other strategies, but they do not consist in the Jacobian matrix evaluated on some average state.